# DANISH RAHMAN

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#### **EDUCATION**

#### **COLUMBIA UNIVERSITY**

M.S. in Mechanical Engineering, Concentration in Robotics and Control

#### **TEXAS A&M UNIVERSITY**

B.S. in Mechanical Engineering

Pi Tau Sigma, Mechanical Engineering Honors Society

#### **TECHNICAL SKILLS**

- Technical Skills: Linux, Simulink, LabVIEW, SolidWorks, 3-D Prototyping, Wireshark, PvBullet, Git, JIRA, and Confluence •
- Programming: Python, PyTorch, MATLAB, C
- Languages: English (native, full proficiency), Urdu (native, full proficiency)

#### WORK EXPERIENCE

# **RHEINMETALL BARZAN ADVANCED TECHNOLOGIES (RBAT)**

#### **Systems Engineer II**

- Developed and executed an extensive set of V&V test plans and procedures for vehicle performance for a fleet of electrified unmanned ground vehicles in a desert environment, focused on power consumption, thermal optimization, and vehicle maneuverability in line with MIL-STD 810G standards.
- Headed the Sensor Suite Project with a cross-functional team; developed and 3-D prototyped a physical sensor system of IMUs, • thermocouples, voltage, current and rotational sensors; integrated with LabVIEW for data acquisition, collection, and analysis of performance parameters such as slippage ratio and power consumption for scenario-based operational limits.
- Facilitated the system design, architecture, and integration of state-of-the-art 8x8 electrified unmanned ground vehicles (UGVs)
- Defined system and software requirements for the development of a UGV Command and Control (C2) Software, focusing on • autonomous features such as collision avoidance, waypoint navigation, target tracking, motion planning and mission execution.

#### **Mechanical Engineer I**

- Conducted detailed data analysis and performance evaluation of lithium phosphate batteries, to simulate and determine battery characteristics such as charging and discharging curves in varying operational environments.
- Developed and fabricated a miniature UGV prototype, using a customized motion controller fused with off-the-shelf sensors such as LiDAR, cameras and IMUs.
- Performed electro-mechanical FMEA and root-cause troubleshooting activities for critical failures of vehicle prototypes, including GPS systems, LiDAR, navigation systems, dead reckoning, lithium-ion battery system failure and vehicle drivetrain malfunctions.

### **RESEARCH EXPERIENCE AND PROJECTS**

### **COLUMBIA UNIVERSITY**

#### **Robotics and Rehabilitation Lab (ROAR Lab)**

- Worked on the Mobile Tethered Pelvic Assist Device (mTPAD) Project, developing a novel solution to augment motion stability in elderly people, and patients of Parkinson's and Cerebellar ataxia.
- Collected and conducted statistical analysis (pairwise t-testing and ANOVA) of locomotive data using EMGs, LabVIEW and data acquisition systems to identify trends in gait position and weight distribution for different patients.

#### Actuated Upper Limb Orthosis for ALS and Parkinson's Patients with Independent Torque Control Jan. 2023 – Sep. 2023

- Designed and simulated a 5 DOF arm orthosis to enhance and facilitate reaching and grasping functionality for patients of neurodegenerative diseases such as ALS and Parkinsons
- Implemented a robust control scheme to account for spinal muscular atrophy and hand tremors to ensure optimal arm trajectory. Aug. 2022 – Dec. 2022

# **Quadrupedal Walking Robot**

- Designed, 3D-prototyped and fabricated a quadrupedal walking robot as part of an engineering team aimed at replicating the engineering lifecycle of a stand-alone engineering product.
- Utilized inverse kinematics and parametric mapping to plan gait and motion trajectories for the quadrupedal, while optimizing its performance through physics simulation on PyBullet.

#### **TEXAS A&M UNIVERSITY**

#### Founding Team Member, SAE Supermileage

Designed and developed a fuel-efficient three-wheel prototype vehicle for the Society of Automotive Engineers (SAE) Supermileage Competition 2018.

# **RELEVANT ACTIVITIES AND AWARDS**

# **TEXAS A&M UNIVERSITY**

### Vice-President Internal, Student Engineers' Council

- Led a student-run organization focused on liaising between the student body and the TAMU administration and faculty.
- Awarded the Troy Marschang Award for Leadership Excellence, and the Buck Weirus Spirit Award.

Sep. 2018 – Apr. 2021

Aug. 2022 – Sep. 2023

New York, NY

Dec. 2023

May 2018

Doha. Oatar

*May* 2021 – *Jul.* 2022

Aug. 2017 – Jun. 2018

Sep. 2016 – Jun. 2018